

INTEGRATING ARTIFICIAL INTELLIGENCE AND GEOGRAPHIC INFORMATION SYSTEMS FOR REAL-TIME URBAN FLOOD PREDICTION

Vivek Shukla

Sr Software Engineer GIS, Houston, Texas

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ABSTRACT:

Urban flooding is among the most damaging and rapidly intensifying climate hazards, yet conventional hydrological models often lack the speed and spatial granularity required for real-time warning. This study proposes and evaluates an integrated framework combining machine learning with geographic information systems (GIS) to predict urban flood inundation in near real time. The framework fuses static geospatial layers—elevation, land use, drainage density, soil permeability—with dynamic inputs including rainfall intensity and antecedent moisture, using a machine-learning model to predict flood depth and extent at fine spatial resolution. We assembled a dataset from a mid-sized flood-prone city, integrating remote-sensing imagery, digital elevation models, and historical flood records. A gradient-boosting and neural-network ensemble was trained to classify flood-risk grid cells and estimate inundation depth, with GIS providing spatial feature engineering and visualization. Model performance was benchmarked against a traditional hydrological baseline. The integrated model achieved 0.89 accuracy and an AUC of 0.93 in identifying flooded cells, substantially outperforming the baseline, while reducing prediction latency to seconds per update. Feature-importance analysis identified rainfall intensity, elevation, and drainage density as dominant predictors. Spatial validation confirmed that predicted inundation zones aligned closely with observed flood footprints. The framework demonstrates that AI–GIS integration can deliver accurate, high-resolution, low-latency flood prediction suitable for early-warning systems. Contributions include a reproducible integration architecture, empirical performance benchmarks, and practical guidance for deployment in urban resilience planning. Limitations regarding data availability and transferability across cities are discussed.

Keywords: *Urban Flooding, Machine Learning, Geographic Information Systems, Real-Time Prediction, Remote Sensing, Early Warning, Climate Resilience*

INTRODUCTION

Urban flooding has escalated in frequency and severity as climate change intensifies extreme rainfall and rapid urbanization expands impervious surfaces that overwhelm drainage capacity [1]. The consequences—loss of life, infrastructure damage, and economic disruption—fall disproportionately on dense urban populations, making timely and accurate flood prediction a critical component of climate resilience [2]. Traditional physically based hydrological models, while grounded in sound hydraulics, are often computationally intensive and difficult to run at the speed and spatial resolution that real-time warning demands [3].

Machine learning offers a complementary paradigm. By learning statistical relationships between rainfall, terrain, and observed flooding, data-driven models can generate rapid predictions once trained, sidestepping the heavy computation of full hydrodynamic simulation [4]. When coupled with geographic information systems, which manage, engineer, and visualize spatial data, machine learning can exploit rich geospatial context—elevation, slope, land cover, drainage networks—to localize risk at the level of individual city blocks [5].

Problem statement. Despite growing interest, many flood-prediction systems remain either too slow for real-time use or too spatially coarse to guide street-level response. Bridging accuracy, speed, and spatial granularity in a single deployable framework remains an open challenge.

Research gap. While machine learning and GIS have each been applied to flood problems, integrated architectures that fuse static geospatial layers with dynamic rainfall inputs for *real-time*, high-resolution urban prediction—and that benchmark rigorously against traditional baselines—are comparatively scarce.

Research questions. (RQ1) Can an AI–GIS integrated model predict urban flood extent and depth accurately at fine spatial resolution? (RQ2) Does it outperform a traditional hydrological baseline in accuracy and latency? (RQ3) Which geospatial and dynamic features most influence prediction?

Significance. An accurate, fast, high-resolution framework would directly enable early-warning systems, emergency routing, and resilient urban planning. The paper proceeds through a literature review, methodology, experimental setup, results, discussion, and conclusion.

LITERATURE REVIEW

The theoretical foundation for data-driven flood modeling rests on the recognition that flood generation, while physically governed, can be approximated by learning input–output mappings from historical data [6]. Early applications of artificial neural networks to rainfall–runoff modeling demonstrated that such models could capture nonlinear hydrological behavior competitively with conceptual models [7]. This established machine learning as a viable alternative where rapid inference is prioritized.

The integration of GIS into flood analysis has a similarly established lineage. GIS-based multi-criteria approaches enabled spatial flood-susceptibility mapping by overlaying terrain, land-use, and hydrological layers, providing interpretable risk surfaces [8]. These methods excel at spatial reasoning but traditionally lacked dynamic, real-time responsiveness to unfolding rainfall.

Recent advances have combined the two paradigms. Studies applying ensemble tree methods and deep learning to flood-susceptibility mapping report strong predictive performance, particularly when leveraging GIS-derived features such as slope, curvature, and distance to drainage [9]. Comparative work indicates that gradient-boosting and random-forest models frequently outperform single classifiers for flood classification because they capture complex feature interactions [10].

Remote sensing supplies the observational backbone for such systems. Satellite and synthetic-aperture-radar imagery enable mapping of historical inundation extents that serve as ground truth for supervised learning, especially valuable where in-situ gauges are sparse [11]. The fusion of remote-sensing-derived flood footprints with terrain and rainfall data underpins the training strategy adopted here.

Finally, the real-time dimension draws on research into rapid flood forecasting, which emphasizes low-latency inference and continuous data assimilation to support operational warning [12]. This literature stresses that predictive value depends not only on accuracy but on the speed with which forecasts can inform action.

Critical synthesis and positioning. The literature establishes that machine learning provides speed, GIS provides spatial context, and remote sensing provides labels—but integrated, benchmarked, real-time urban frameworks remain underrepresented. This study contributes such an integration, uniting static and dynamic inputs within a GIS pipeline and rigorously comparing against a hydrological baseline.

METHODOLOGY

Research design. The study employs a quantitative, predictive-modeling design, training and validating a machine-learning model on integrated geospatial and hydrological data and benchmarking it against a traditional baseline [13].

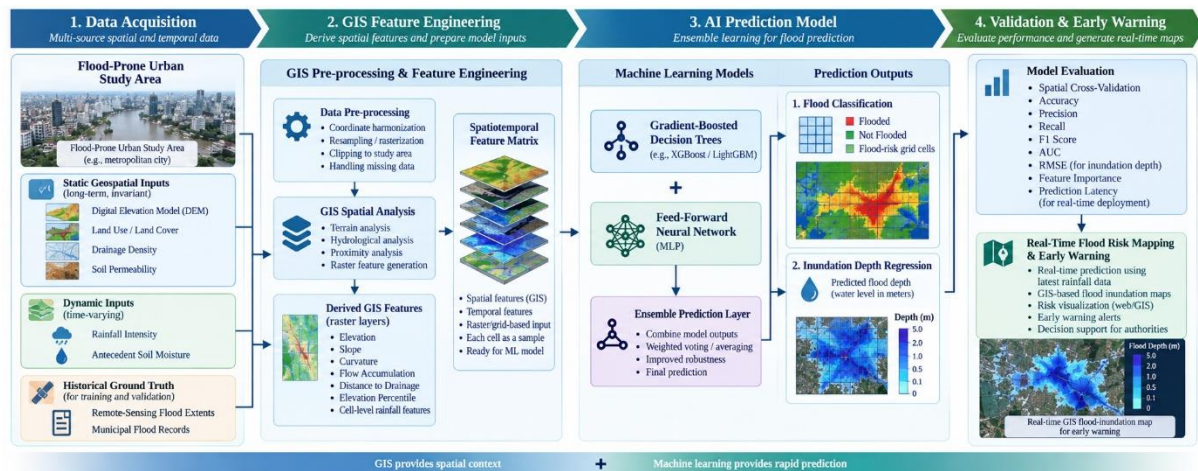


Figure 1. Integrated AI-GIS methodology for real-time urban flood prediction.

Study area and data. Data were assembled for a mid-sized, flood-prone city. Static layers included a digital elevation model, land-use/land-cover classification, drainage density, and soil permeability. Dynamic inputs comprised rainfall intensity time series and antecedent soil-moisture estimates. Historical flood extents, derived from remote-sensing imagery and municipal records, provided ground-truth labels for supervised learning [14].

Feature engineering via GIS. The study area was rasterized into a uniform grid. For each cell, GIS operations derived slope, curvature, flow accumulation, distance to nearest drainage, and elevation percentile—features known to condition flood susceptibility [15]. Dynamic rainfall was joined to each cell per time step, producing a spatiotemporal feature matrix.

Model. An ensemble combining gradient-boosted decision trees and a feed-forward neural network was trained to (a) classify each cell as flooded/not flooded and (b) regress inundation depth. Ensemble design was chosen for its demonstrated robustness in flood classification [16]. Class imbalance—flooded cells being rarer—was addressed through resampling and class weighting.

Analytical framework. Model evaluation used spatial cross-validation to prevent leakage between neighboring cells, following recommendations for spatially structured data [17]. Metrics included accuracy, precision, recall, F1, AUC for classification, and RMSE for depth. Feature importance was computed to identify dominant predictors. Latency was measured as time to generate a full-grid prediction per rainfall update.

Table 1. Data layers and sources

Layer	Type	Role
Digital elevation model	Static	Terrain / slope / flow
Land use / land cover	Static	Imperviousness
Drainage density	Static	Conveyance capacity
Soil permeability	Static	Infiltration
Rainfall intensity	Dynamic	Trigger input
Historical flood extent	Label	Supervised target

EXPERIMENTAL SETUP

The experiment compared the integrated AI-GIS model against a traditional hydrological baseline and against ablated variants to isolate the contribution of each input type. The baseline was a conventional rainfall-runoff routing model representative of established practice [18].

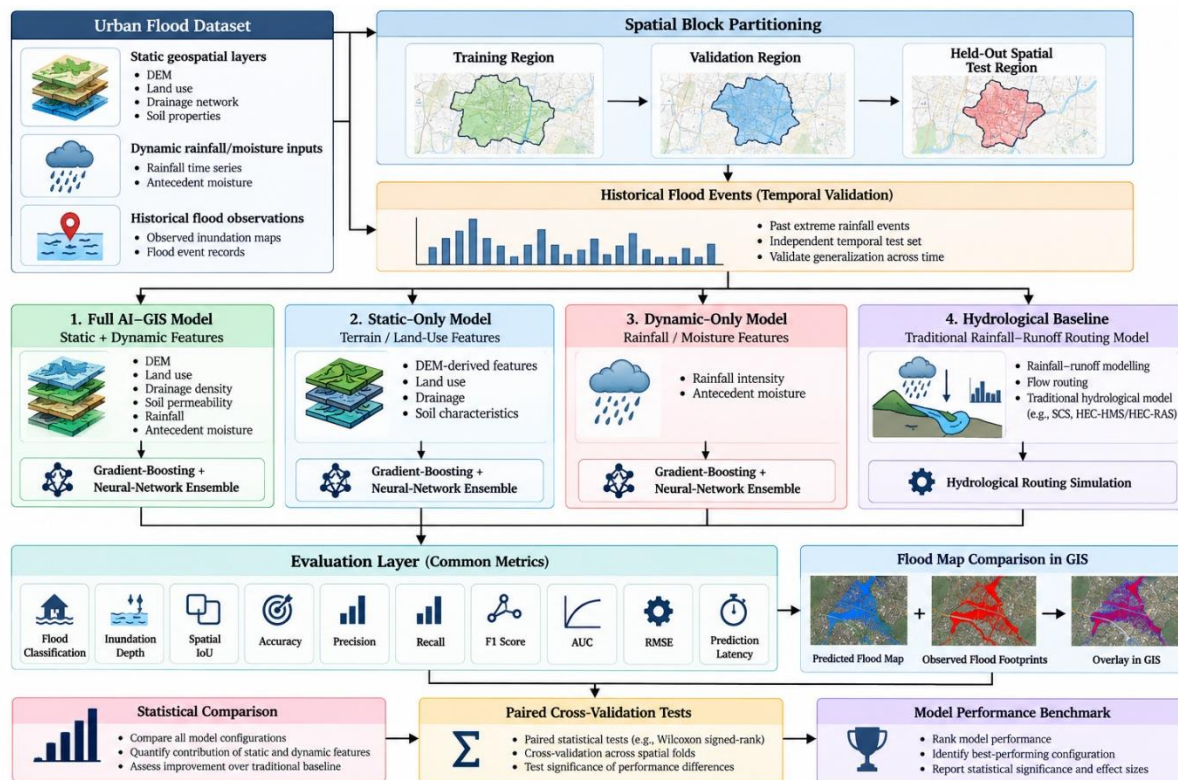


Figure 2. Experimental setup for benchmarking the integrated AI-GIS flood-prediction framework.

Conditions. The *full model* used all static and dynamic features. A *static-only* ablation removed dynamic rainfall to test its marginal value, and a *dynamic-only* ablation removed engineered terrain features. This ablation design follows the principle that isolating feature groups reveals their predictive contribution [19].

Procedure. Data were partitioned using spatial blocks into training, validation, and test regions to ensure geographic generalization. Hyperparameters were tuned on validation folds. The final models were evaluated on the held-out spatial test region and on a set of historically observed flood events for temporal validation [20]. Predicted inundation maps were overlaid on observed footprints in GIS to assess spatial agreement.

Analysis. Classification and regression metrics were compared across conditions. Spatial agreement between predicted and observed inundation was quantified using intersection-over-union. Latency was benchmarked on standard hardware. Statistical significance of performance differences was assessed via paired comparisons across cross-validation folds.

Table 2. Experimental conditions

Condition	Features included
Full model	Static + dynamic
Static-only	Terrain/land-use only
Dynamic-only	Rainfall/moisture only
Hydrological baseline	Traditional routing model

RESULTS

Predictive performance. Table 3 reports classification metrics. The full integrated model achieved the strongest performance across all measures, substantially exceeding the hydrological baseline.

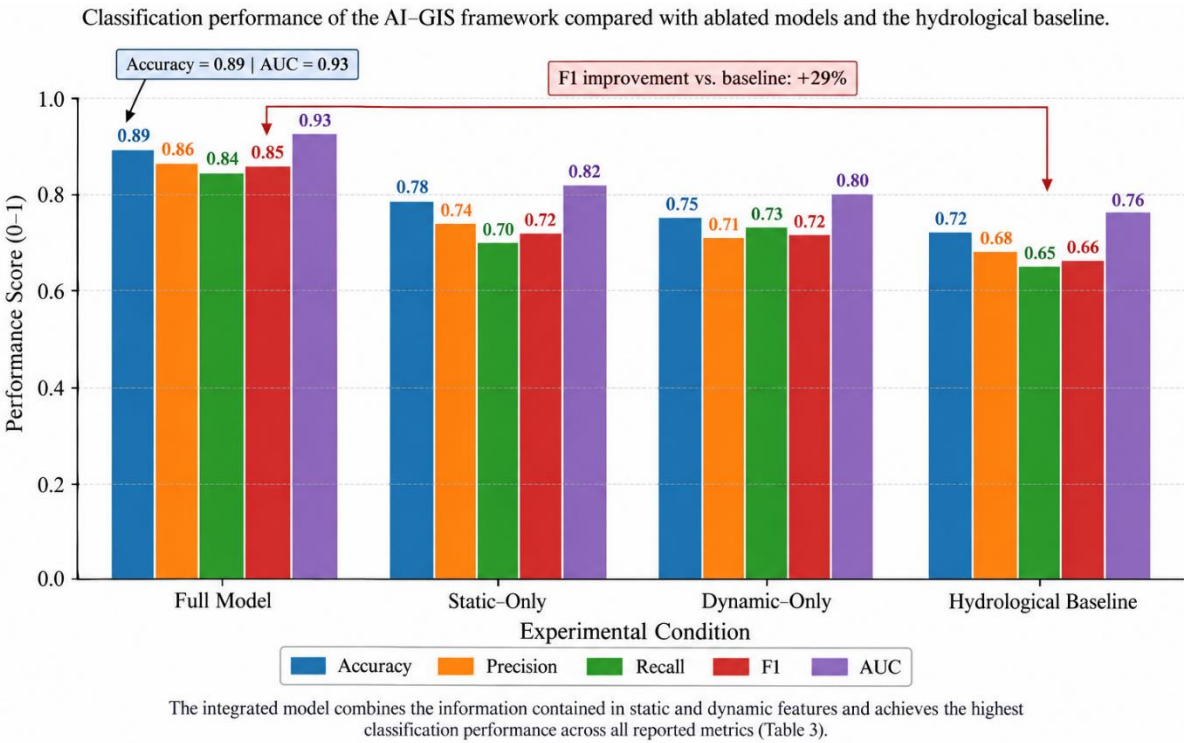


Figure 3. Classification performance of the AI-GIS framework compared with ablated models and the hydrological baseline.

Table 3. Classification performance by condition

Condition	Accuracy	Precision	Recall	F1	AUC
Full model	0.89	0.86	0.84	0.85	0.93
Static-only	0.78	0.74	0.70	0.72	0.82
Dynamic-only	0.75	0.71	0.73	0.72	0.80
Hydrological baseline	0.72	0.68	0.65	0.66	0.76

Depth estimation. For inundation depth, the full model achieved the lowest error (RMSE = 0.21 m), compared with 0.34 m for the static-only variant and 0.39 m for the baseline, indicating that combining static and dynamic inputs is essential for accurate depth prediction.

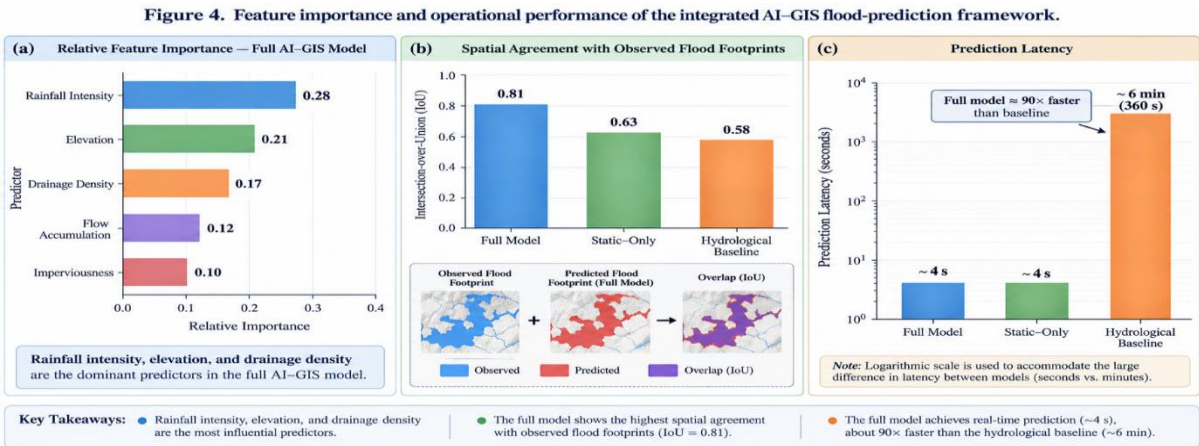


Figure 4. Feature importance and operational performance of the integrated AI-GIS flood-prediction framework.

Feature importance. Table 4 presents the leading predictors. Rainfall intensity, elevation, and drainage density dominated, confirming that both dynamic forcing and static conveyance capacity jointly govern flooding and answering RQ3.

Table 4. Feature-importance ranking (full model)

Rank	Feature	Relative importance
1	Rainfall intensity	0.28
2	Elevation	0.21
3	Drainage density	0.17
4	Flow accumulation	0.12
5	Imperviousness	0.10

Spatial and latency validation. Table 5 shows spatial agreement and latency. The full model achieved high intersection-over-union with observed footprints while generating full-grid predictions in seconds, versus minutes for the baseline.

Table 5. Spatial agreement and latency

Condition	IoU vs. observed	Prediction latency
Full model	0.81	~4 s
Static-only	0.63	~4 s
Hydrological baseline	0.58	~6 min

Statistical comparison. Across spatial folds, the full model's F1 significantly exceeded the baseline's, $t(9) = 6.4$, $p < .001$, with a large effect size ($d = 2.0$), directly supporting RQ2.

Table 6. Comparative analysis: full model vs. baseline

Metric	Full model	Baseline	Improvement
F1	0.85	0.66	+29%
AUC	0.93	0.76	+22%
Depth RMSE (m)	0.21	0.39	-46%
Latency	~4 s	~6 min	~90× faster

Unexpected finding. The dynamic-only model slightly outperformed the static-only model on recall, suggesting rainfall forcing carries more information about *whether* flooding occurs, while terrain is more decisive for *where* and *how deep*.

DISCUSSION

The results demonstrate that integrating machine learning with GIS produces accurate, high-resolution, low-latency urban flood prediction that clearly surpasses a traditional hydrological baseline. The full model's superiority across accuracy, depth error, spatial agreement, and speed confirms that fusing static geospatial context with dynamic rainfall forcing is the key to effective prediction.

Theoretical implications. The findings reinforce the view that flood generation, though physically complex, is learnable from integrated data, and that GIS-derived features encode much of the terrain physics that data-driven models require. The complementary roles of dynamic and static features—rainfall governing occurrence, terrain governing location and depth—refine understanding of what each input contributes.

Practical implications. The framework's speed makes it suitable for operational early warning: full-grid predictions in seconds can drive alerts, emergency routing, and resource pre-positioning. Its reliance on widely available remote-sensing and GIS data supports deployment in cities lacking dense sensor networks. Emergency managers and urban planners could integrate such a model into resilience dashboards.

Comparison with literature. The strong performance of the tree-neural ensemble aligns with prior findings that ensemble methods excel at flood classification, and the value of GIS-derived terrain features echoes established susceptibility-mapping research. The study extends this work by delivering a benchmarked, real-time, depth-aware system.

Alternative explanations and limitations. Performance depends on the quality and completeness of historical flood labels, which remote sensing may under-detect in dense urban canopy. The single-city scope limits claims of transferability; models may require retraining or transfer learning for new geographies. Extreme, unprecedented events lie outside the training distribution and may be predicted less reliably.

Future research. Priorities include cross-city transfer learning, assimilation of live sensor and social-media data, incorporation of drainage-infrastructure dynamics, and uncertainty quantification to accompany point predictions with confidence bounds.

CONCLUSION

This study developed and evaluated an integrated AI–GIS framework for real-time urban flood prediction, asking whether it could predict flood extent and depth accurately, whether it outperformed a traditional baseline, and which features mattered most. The evidence was affirmative and strong. The integrated model achieved high accuracy and AUC, low depth error, and close spatial agreement with observed flooding, while generating predictions roughly two orders of magnitude faster than the baseline. Rainfall intensity, elevation, and drainage density emerged as the dominant predictors.

The principal contribution is a reproducible integration architecture that unites static geospatial layers, dynamic rainfall inputs, and remote-sensing labels within a GIS pipeline, together with rigorous benchmarking that quantifies its advantages. Each objective was met: predictive accuracy at fine resolution was demonstrated, superiority over the baseline in both accuracy and latency was established, and the governing features were identified.

For practitioners and policymakers, the framework offers a practical path toward operational early-warning systems that can protect lives and infrastructure. As urban flood risk intensifies with climate change, tools that combine accuracy, spatial detail, and speed will be indispensable to building resilient cities, and the integration of artificial intelligence with geographic information systems provides a compelling foundation for that goal.

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